# Truncated Taylor approximation of Loewner dynamics Supervised by Prof. Dmitry Belyaev and Prof. Terry Lyons 

Vlad Margarint

Dept. of Mathematics, University of Oxford vlad.margarint@maths.ox.ac.uk

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## Overview

(1) Introduction to SLE
(2) The Rough Paths approach: Explicit truncated Taylor approximation
(3) Perspectives
(4) References

## Conformal maps

- Examples of conformal maps from upper halfplane with a slit to the upper halfplane $\mathbb{H}$.


2) 



## Conformal maps and the Loewner equation

- In general, for a non-self crossing curve $\gamma(t):[0, \infty) \rightarrow \overline{\mathbb{H}}$ with $\gamma(0)=0$ and $\gamma(\infty)=\infty$, we consider the simply connected domain $\mathbb{H} \backslash \gamma([0, t])$.

- Using the Riemann Mapping Theorem for the simply connected domain $\mathbb{H} \backslash \gamma([0, t])$, we have a three real parameter family of conformal maps $g_{t}: \mathbb{H} \backslash \gamma([0, t]) \rightarrow \mathbb{H}$.
- Loewner Equation encodes the dependence between the evolution of the maps $g_{t}$ when the curve $\gamma([0, t])$ grows.


## Description of the conformal maps

- Setting the behaviour of the mapping at $\infty$ as $g_{t}(\infty)=\infty$ and $g_{t}^{\prime}(\infty)=1$, we write the Laurent expansion at $\infty$ of $g_{t}$ as

$$
g_{t}(z)=z+b_{0}+\frac{b_{1}}{z}+\frac{b_{2}}{z^{2}}+\ldots
$$

- We fix the third paramater by choosing $b_{0}=0$.
- The coefficient $b_{1}=b_{1}(\gamma([0, t]))$ is called the half-plane capacity of $\gamma(t)$ and is proved to be an additive, continous and increasing function. Hence, by reparametrizing the curve $\gamma(t)$ such that $b_{1}(\gamma([0, t]))=2 t$, we obtain

$$
g_{t}(z)=z+\frac{2 t}{z}+\ldots
$$

## Conformal maps and the Loewner equation

- Is there a way to use $g_{t}$ to find $g_{t+d t}$ ?

- In order to answer this question, we have to describe to find a way to describe the mapping $m_{t, d t}: \mathbb{H} \backslash g_{t}(\gamma[t, t+d t]) \rightarrow \mathbb{H}$.


## The Loewner equation and the square root map

- The square root map that we investigated in the beginning gives the description of the 'infinitesimal mapping' $m_{t, d t}$.

- Heuristically, $m_{t, d t}(z)=U_{t+d t}+\sqrt{\left(z-U_{t}\right)^{2}+2 d t} \approx z+\frac{2 d t}{z-U_{t}}$.
- Furthermore, $g_{t+d t}(z) \approx g_{t}(z)+\frac{2 d t}{g_{t}(z)-U_{t}}$.
- We obtain the Loewner Differential Equation

$$
\partial_{t} g_{t}(z)=\frac{2}{g_{t}(z)-U_{t}}, \quad g_{0}(z)=z
$$

## Loewner equation and random curves in the upper half-plane

- So far, we adopted the perspective that given the curve $\gamma_{t}$, the conformal maps $g_{t}$ must satisfy

$$
\partial_{t} g_{t}(z)=\frac{2}{g_{t}(z)-U_{t}}, \quad g_{0}(z)=z
$$

with $U_{t}=g(\gamma(t))$.

- From now on, we take the dual perspective. Given the driving function $U_{t}:[0, \infty) \rightarrow \mathbb{R}$, we determine $g_{t}$. Then, the maps $g_{t}$ determine the curve $\gamma(t)$.
- To output random continous curves, $U_{t}$ has to be a random continous driver. Moreover, the random driver $U_{t}$ induces a law on the curves $\gamma(t)$.


## Definition of SLE and dependence on $\kappa$

## Definition

Let $B_{t}$ be a standard real Brownian motion starting from 0. The chordal $\operatorname{SLE}(\kappa)$ is defined as the law on curves induced by the solution to the following ordinary differential equation

$$
\partial_{t} g_{t}(z)=\frac{2}{g_{t}(z)-\sqrt{\kappa} B_{t}}, \quad g_{0}(z)=z
$$



Figure: SLE(1): Credit Prof. Vincent Beffara


Figure: SLE(3.5): Credit Prof. Vincent Beffara


Figure: SLE(4.5): Credit Prof. Vincent Beffara


Figure: SLE(6): Credit Prof. Vincent Beffara

## SLE phase transitions

- It is proved that there are two phase transitions when $\kappa$ varies between 0 and $\infty$.

$$
\text { Up to } \kappa=4 \quad 4<\kappa<8 \quad \kappa=8 \text { and bigger }
$$



- The argument uses the phase transition of the Bessel process on the real line.
- In order to show this, consider the process $d Z_{t}=\frac{2 d t}{\kappa Z_{t}}-d B_{t}$, where $Z_{t}:=\frac{1}{\sqrt{\kappa}} g_{t}-B_{t}$.


## SLE phase transitions

- When started with a real initial value, the process $d Z_{t}=\frac{2 d t}{\kappa Z_{t}}-d B_{t}$ is a real valued Bessel process with parameter $a=\frac{2}{\kappa}$.
- If $\kappa \leq 4$, then with probability one, the hitting time of zero $T_{x}=\infty$ for all non-zero $x \in \mathbb{R}$.
- If $\kappa \geq 4$, then with probability one, the hitting time of zero $T_{x}<\infty$ for all non-zero $x \in \mathbb{R}$.
- If $4<\kappa<8$ and $x<y \in \mathbb{R}$, then $\mathbb{P}\left(T_{x}=T_{y}\right)>0$.
- If $\kappa \geq 8$, then with probability one, $T_{x}<T_{y}$ for all reals $x<y$.


## The Rough Paths perspective

- We consider the backward Loewner differential equation

$$
\partial_{t} h_{t}(z)=\frac{-2}{h_{t}(z)-\sqrt{\kappa} B_{t}}, \quad h_{0}(z)=z
$$




Figure: The images of a thin rectangle under the forward Loewner evolution (left) and backward Loewner evolution(right) for $\kappa=0$.

- Finally, we obtain the following RDE in the upper half plane:

$$
d z_{t}=\frac{-2}{z_{t}} d t-\sqrt{\kappa} d B_{t}
$$

## The Lie bracket of the two vector fields and the uncorrelated diffusions

- We study an approximation to the solution of the RDE

$$
d z_{t}=\frac{-2}{z_{t}} d t-\sqrt{\kappa} d B_{t} .
$$

## Remark

For $z=x+i y$, we have that $\left[\frac{-2 x}{x^{2}+y^{2}} \frac{\partial}{\partial_{x}}+\frac{2 y}{x^{2}+y^{2}} \frac{\partial}{\partial_{y}}, \sqrt{\kappa} \frac{\partial}{\partial_{x}}\right]=\frac{-2 \sqrt{\kappa}}{z^{2}}$.

## Proposition

Let $\epsilon>0$. At space scale $\epsilon$ and time scale $\epsilon^{2}$ the increment of the horizontal Brownian motion $B_{t}$ and the increment of the area process between $t$ and $B_{t}$ are uncorrelated. Moreover, they give the same order contribution in the approximation.

## The field of ellipses

- We consider the field of ellipses associated with this diffusion. Note that these ellipses should be shifted along the drift.
- At this specific scales the directions and lengths of the axes are computed explicitly in terms of the argument $\theta$ and the parameter $\kappa$.


Figure: A schematic representation of the field of ellipses. The drift direction is represented in green.

## Explicit dynamics and local truncation error up to the second level

## Proposition

Fix $\epsilon>0$. The truncated second level order Taylor approximation $\tilde{z}_{t}$ of the Loewner $R D E$ started from $\left|z_{0}\right|=\epsilon$, at time $\epsilon^{2}>0$ is an explicit function of $\kappa, z_{0}$ and $\epsilon$. Moreover, the local truncation error of the truncated Taylor approximation is $O(\epsilon)$.

- Important: the contribution of the second order approximation term

$$
\int_{0}^{\epsilon^{2}} \frac{-2 \sqrt{\kappa}}{Z_{t}^{2}} d A_{t} \text { is } O(\epsilon)
$$

$$
\text { since } \frac{1}{\left|Z_{0}\right|^{2}}=\frac{1}{\epsilon^{2}} \text { and } A_{\epsilon^{2}}=\frac{1}{2}\left(\int_{0}^{\epsilon^{2}} B_{s} d s-\int_{0}^{t} s d B_{s}\right) \text { is } O\left(\epsilon^{3}\right) \text {. }
$$

## Elements of the proof

- The diffusive part of the approximation is described by the ellipses given by

$$
\left(T\left[\begin{array}{l}
u \\
v
\end{array}\right]\right)^{t}\left[\begin{array}{ll}
A & B \\
C & D
\end{array}\right] T\left[\begin{array}{l}
u \\
v
\end{array}\right]=1
$$

where

$$
T=\left[\begin{array}{cc}
\sqrt{\kappa \epsilon^{2}} & -\operatorname{Re} \frac{1}{z^{2}} \sqrt{\frac{\epsilon^{6}}{3} \kappa} \\
0 & -\operatorname{lm} \frac{1}{z^{2}} \sqrt{\frac{\epsilon^{6}}{3} \kappa}
\end{array}\right] .
$$

- We obtain the explicit squares of semi-axis of the ellipses $a_{1,2}(\kappa, \theta, \epsilon)$ as inverses of the solutions to

$$
\lambda^{2}-\lambda\left(\frac{1}{\kappa \epsilon^{2}}+\frac{3}{\kappa \epsilon^{6} \operatorname{Im}^{2} \frac{1}{z^{2}}}+\frac{\operatorname{ctg}^{2}(-2 \theta)}{\kappa \epsilon^{2}}\right)+\frac{3}{\kappa^{2} \epsilon^{8} \operatorname{Im}^{2} \frac{1}{z^{2}}}=0
$$

## Future perspectives

- Compare the probability of crossing a sequence of centered annuli for the Forward Loewner evolution given by the Rough Paths approach with the one given by the typical Bessel process approach.
- Similarly, study the dynamics given by the Rough Paths approach on the boundary.
- Study in polar coordinates $\arg \left(z_{t}\right)$ using the logarithm mapping.


## Thank you for your attention!

## References

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